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A New View on Statistical Inference
Part IV
Tow Action Problems

by

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Abstract.

Let $I_A(x)$ be an indicator function such that for any set A $I_A(x)=1$,
if $x \in A$; $=0$, if $x \notin A$.

We consider two action problems under the density

$$f(x|\theta) = c^{-1} I_{(0+\eta_1, 0+\eta_2)}(x), \quad \forall \theta$$

where $c = \eta_2 - \eta_1 (> 0)$ and real numbers η_1 and η_2 .

§ 1. Two action problem.

Let $\Omega = (-\infty, \infty)$ be a parameter space and let Ω_0 and Ω_1 be the subspace of Ω such that $\Omega_0 \cup \Omega_1 = \Omega$ and $\Omega_0 \cap \Omega_1 = \emptyset$. In this paper we consider the two-action problem of testing hypotheses $H_0: \theta \in \Omega_0$ versus $H_1: \theta \in \Omega_1$, provided the random observations X_1, \dots, X_n from the population with density $f(x|\theta)$. Assume that a_i denotes the action deciding in favor of H_i ($i=0,1$).

Let $L(\theta, a)$ be the loss function such that

$$(1) \quad L(\theta, a_0) = \begin{cases} 1, & \text{if } \theta \in \Omega_1 \\ 0, & \text{if } \theta \in \Omega_0 \end{cases}$$

and $L(\theta, a_1) = 1 - L(\theta, a_0)$.

Let $\underline{Y} = Y(X_1, \dots, X_n)$ be the underlined statistic with density $g(y|\theta)$.

We denote by $\delta(y, \cdot)$ a decision rule showing the probability distribution on $A = \{a_0, a_1\}$. Namely,

$$(2) \quad \delta(y, a_0) + \delta(y, a_1) = 1.$$

For given y , the loss function of δ is given by

$$(3) \quad \begin{aligned} L(\theta, \delta(y, \cdot)) &= E_{\theta}(\delta(y, \cdot)) (L(\theta, a)) \\ &= \int L(\theta, a) \, d\delta(y, a), \quad \forall \theta. \end{aligned}$$

The risk function $R(\theta, \delta)$ is of form

$$(4) \quad R(\theta, \delta) = E_{Y|\theta} (L(\theta, \delta(Y, \cdot))) = \int L(\theta, a) \, d\delta(y, a) \, g(y|\theta) \, dy.$$

Namely, for $\theta \in \Omega_0$

$$(5) \quad \begin{aligned} R(\theta, \delta) &= E_{Y|\theta} (\delta(Y, a_0)L(\theta, a_0) + \delta(Y, a_1)L(\theta, a_1)) \\ &= \int \delta(y, a_1) \, g(y|\theta) \, dy = E_{\theta}(\delta(Y, a_1)). \end{aligned}$$

In the same way, for $\theta \in \Omega_1$

$$(6) \quad R(\theta, \delta) = E_{Y|\theta} (L(\theta, \delta(Y, \cdot))) = \int \delta(y|a_0) \, g(y|\theta) \, dy = E_{\theta}(\delta(Y, a_0)).$$

Hereafter, we let $\Omega_0 = \{\theta_0\}$ with real number θ_0 , and $\Omega_1 = \{\theta: \theta \neq \theta_0\}$.

We also let $\delta(y, a_i)$ abbreviate to $\delta_i(y)$ ($i=0,1$).

In this paper we consider the decision rules of form

$$(7) \quad \delta_1(y) = \begin{cases} 1, & \text{if } y \leq y_1 \text{ or } y \geq y_2 \\ 0, & \text{if } y_1 < y < y_2 \end{cases}$$

and $\delta_0(y) = 1 - \delta_1(y)$, where y_1 and y_2 are real numbers such that $y_1 < y_2$.

In the next section we consider the distribution with density of form $f(x|\theta) = c^{-1} I_{(\theta+\eta_1, \theta+\eta_2)}(x)$

§2. $f(x|\theta) = c^{-1} I_{(\theta+\eta_1, \theta+\eta_2)}(x)$ -- Case.

In this section we consider the population with density

$$(8) \quad f(x|\theta) = c^{-1} I_{(\theta+\eta_1, \theta+\eta_2)}(x), \quad \text{for } \theta \in (-\infty, \infty)$$

where η_1 and η_2 are real numbers with $c = \eta_2 - \eta_1 (> 0)$.

Let $X_{(i)}$ be the i -th smallest observation of X_1, \dots, X_n , taken randomly from the population with density $f(x|\theta)$. In this section we use an unbiased estimator $Y = (X_{(1)} + X_{(n)} - \eta_0) / 2$ ($\eta_0 = \eta_1 + \eta_2$) to get the optimal decision $\delta_0(y)$ for deciding a_0 . Applying variable transformations $Y = (X_{(1)} + X_{(n)} - \eta_0) / 2$ and $Z = X_{(1)}$ to the joint density of $(X_{(1)}, X_{(n)})$ and taking marginal probability density function (p.d.f.) of Y as follows:

$$(9) \quad g(y|\theta) = \begin{cases} nc^{-n} (c-2|y-\theta|)^{n-1}, & \text{for } -c/2 < y-\theta < c/2 \\ 0, & \text{elsewhere.} \end{cases}$$

To get the optimal interval (y_1, y_2) for deciding a_0 we minimize $y_2 - y_1 (> 0)$, provided that for a real number α with $0 < \alpha < 1$ and for all $\theta \in (-\infty, \infty)$,

$$(10) \quad E_\theta(\delta_0(Y)) = P_\theta[y_1 < Y < y_2] = \int_{y_1}^{y_2} g(y|\theta) dy = 1 - \alpha.$$

Since $g(y|\theta)$ is symmetric at θ , we take $y_1 = \theta - r$ and $y_2 = \theta + r$, and obtain

$$(11) \quad r = c(1 - \alpha^{1/n}) / 2.$$

(We note that the optimal region $(Y-r, Y+r)$ satisfies that for all $\theta \in (-\infty, \infty)$,

$$(12) \quad P_\theta[\theta \in (Y-r, Y+r)] = 1 - \alpha.$$

Letting

$$(13) \quad \delta_1^0(y) = \begin{cases} 1, & \text{if } y < \theta - r \quad \text{or} \quad \theta + r < y, \\ 0, & \text{if } \theta - r < y < \theta + r, \end{cases}$$

and $\delta_0^0(y) = 1 - \delta_1^0(y)$, we get

$$(14) \quad \begin{aligned} R(\theta, \delta^0) &= E_\theta(\delta_1^0(Y)) = \alpha, & \theta \in \Omega_0 \\ R(\theta, \delta^0) &= E_\theta(\delta_0^0(Y)) = 1 - E_\theta(\delta_1^0(Y)) = 1 - \alpha, & \theta \in \Omega_1. \end{aligned}$$

If we especially let

$$(15) \quad \delta_1^*(y) = \delta_1^0(y) \quad \text{and} \quad \delta_0^*(y) = 1 - \delta_1^0(y),$$

then

$$(16) \quad R(\theta_0, \delta^*) = E_{\theta_0}(\delta_1^*(Y)) = \alpha,$$

and

$$(17) \quad R(\theta, \delta^*) = E_\theta(\delta_0^*(Y)) = 1 - E_\theta(\delta_1^*(Y)) \leq 1 - \alpha \leq E_\theta(1 - \delta_1(Y)) = R(\theta, \delta), \quad \text{for } \theta \neq \theta_0,$$

because $E_\theta(\delta_1^*(Y)) \geq \alpha$. So, if $D = \{\delta: R(\theta_0, \delta) = \alpha \text{ and } \delta_1(y) \text{ is of form (7)}\}$,

then δ^* is of best among all $\delta \in D$.